



IIT KANPUR



STARTUP  
INCUBATION AND  
INNOVATION  
CENTRE  
IIT KANPUR

Backed by **SIIC, IIT Kanpur**



**Vedansh- Mapping Drone**

## □ **Specification**

● Endurance	40 min +
● Wind resistance	> 8 m/s
● Flight speed	10 m/s
● Encryption	AES 128 bit encryption
● Range	1 km+ (VLOS as per DGCA)

## □ **Failsafe features**

- Low battery
- GeoFence Breach
- Communication loss
- Terrain Following
- RTL/RTH



**CMOS Sony Sensor**  
**24MP Camera**  
**64GB Storage**

**REACH M2**  
Multi-band RTK GNSS Module

**Altitude**  
**GSD**  
**Side Overlap**  
**Area (typical)**  
**Photogrammetry Accuracy Z**  
**Photogrammetry Accuracy X/Y**

**RTK/PPK**  
**GNSS**  
**Log rate Accuracy**  
**Logging**

**L1&L2, G1 & G2**  
**GPS, GLONASS, Galileo**  
**1 ppm CEP**  
**SD Card upto 16gb**

**120 AGL**  
**3CM**  
**60%**  
**>1 sq km**  
**<15 cm**  
**<10 cm**

## **Precision Data by VEDANSH**



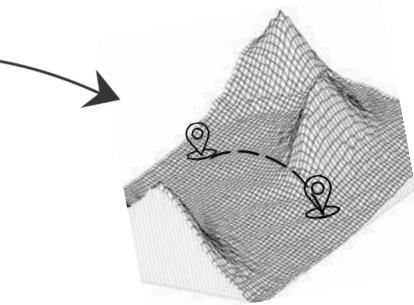
Assemble Landscape  
Data by UAV



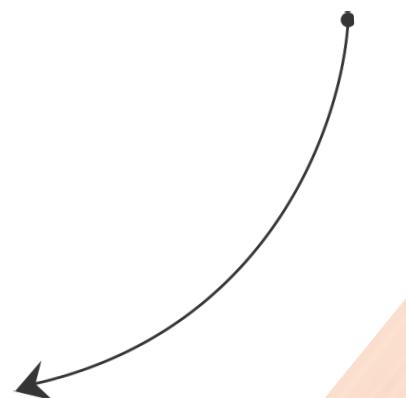
Process Data  
For Protected Output



Unify  
Collected Data



Geographical Identification  
By geo Tagging



Export Data  
In Desired Format

## □ **Custom Payload integration**

### EO-IR Dual vision Payload

Visible Camera Resolution: 1920 X 1080 P

Thermal resolution: 640 X 480P Visible

Camera Zoom: 40X Control Range (PTZ): -45°

C to +135°C(Tilt), -180°C to +180°C (Pan)



### RGB Day Payload

Visible Camera Resolution : 1080p @ 60fps  
Visible Camera Zoom : 10X (Optical)  
Control range (PTZ): -90°to +90° (Tilt),  
-150°to +150°(Pan), -45°to +45°(Roll)

### Mapping Payload

Camera effective megapixel:24.3MP

Sensor type: CMOS Uncompressed

format: RAW, RAW+JPEG Hot shoe for

PPK: Yes Camera weight: 105 g



## Waypoint navigation

It allows the pilot to pre-program a flight path for Vedansh to follow with specific coordinates or points of interest.

## Return to home

It allows Vedansh to automatically fly back to its take-off location or designated home point helping in signal loss, low battery and pilot control loss scenarios.



RTL



## Push, Plug & Perform

This allows the user to quickly deploy the Vedansh to its mission to get maximum awareness.



## Mapping Payload

This mapping payload includes a camera, a gimbal, and a GNSS receiver. The camera is responsible for capturing high-resolution images of the ground. The gimbal stabilizes the camera against platform vibrations, ensuring smooth and clear images. The GNSS receiver provides accurate positioning data for each image, which is used to create accurate and up-to-date maps and surveys.

## Applications



It is used by a variety of professionals, including surveyors, engineers, and construction managers. They are also used by government agencies and research organizations.

Topographic Mapping by conducting high- resolution topographic maps for urban planning, land development, and infrastructure projects

Precision Agriculture by optimizing agricultural practices by utilizing UAVs for crop monitoring, soil analysis, and precision farming.



# Thank You!



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